



Version list Paladin PL18 transmitter software/Paladin PL18 软件版本更新记录

Software version 软件版本	1.0.40	Date 日期	03/2020
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- ▶ **新增功能：**
- 新增高频类型: 支持 FRM302 高频头且可双向通信 (302 需搭配 JR 模块适配器), 且当识别到可调功率版本程序时增加功率可调菜单, 默认未接高频或者接不可调版本高频程序无此功能
 - 新增拨档开关档位可调功能 (可自定义 SWE、SWF、SWG、SWH 开关为 2 档或者 3 档)
 - 新增主界面滑动快捷操作功能 (可自定义上、下、左、右滑动进入部分快捷界面)
 - 新增多用途计时器整分钟语音提示功能 (仅中文有提示)
 - 新增引擎计时器可分配停止和复位开关
 - 新增多用途计时器可分配停止开关
 - 新增闲置报警功能, 用户可自定义报警时间
 - 新增油门熄火点位置可调功能
 - 新增旋钮可分配做微调控件的功能 (注: 固定微调控件的功能不可分配旋钮来作为微调控件)
 - 新增可单独选择开启 / 关闭开关机声音的功能
 - 新增兼容 FTr4 接收机功能 (在连接 FTr4 接收机时, 增加接收机协议中“传感器”选项), 且传感器与 i-BUS 协议切换时增加断开设备提醒窗口
 - 新增开机选择是否开高频功能, 且对应的主界面增加高频未开启 / 未连接的警示图标, 且可点击去开高频
 - 新增配置从机功能, 可以通过发射机配置好从机, 通过 ibus 接口把从接收机与正常对码接收机相连从而达到扩展通道的作用
- ▶ **修改功能：**
- 优化模型命名键盘功能, 增加特殊字符
 - 优化部分界面中的十字光标显示方式
 - 优化界面滑动反馈效果 (滑动到极限时有滑出一半回弹的效果, 直接滑动到极限再滑动无反馈)
 - 优化收油门功能, 让油门熄火功能可以在任意状态下被触发
 - 优化碟形飞菜单下的控件触发方式, 增加旋钮及摇杆的反向触发功能
 - 解决了后续版本升级模型数据复位的问题
 - 修改说明书 & 软件版本更新记录为帮助中心, 并优化后台文件存储方式 (一个二维码地址对应所有说明书、快速操作指南、版本更新记录读取地址)
 - 修改主菜单功能名称“曲线”为“比例和曲线”, 修改对应菜单界面名称“大小舵和曲线”为“比例和曲线”
 - 修改英文字体, 改为无衬线的字体
 - 增加模型名称最大长度为 25, 首页信息栏显示全部模型名称, 其它子页面信息栏默认显示 10 位, 如超出十位, 后面不显示, 显示三点省略号
 - 信息栏去掉接收机电量显示图标, 增加双向协议时接收机未对码提醒并且可以点击进入对码
 - 对滑屏触发交互效果做了调整, 解决慢速滑动时界面停止时间较慢导致的卡屏错觉



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注意事项

- 更新完成后模型被复位
- 更新完成后需重新与接收机对码

以上步骤完成后，可正常使用。

- ▶ **New Features :**
 - New support for the FRM302 RF module (using JR bay adapter) and bidirectional communication with support for power adjustment.
 - Switch customization (the SWE, SWF, SWG, and SWH swapped with 2 or 3 position switches)
 - Added customizable swipe shortcut to the home screen (swipe up, down, left or right to activate your shortcuts)
 - Newly added engine timers stop and reset functions can be assigned switches
 - New multi-purpose timer can be assigned stop switch
 - Added idle alarm function, users can customize alarm trigger time
 - Adjustable throttle stop position
 - Trim functions can now be assigned to knobs (Note: fixed trimming control cannot be assigned as a knob)
 - Added the ability to individually turn sounds the on / off
 - Added FTr4 compatible receiver function (when connecting FTr4 receiver, add "sensor" in receiver setup. When the sensor and i-BUS protocol switch a device disconnect warning will be displayed)
 - Added the option of turning on or off RF completely, and the corresponding main interface adds a high-frequency non-open / not connected alarm with an icon to turn it back on again
 - Added the function to configure a slave. You can configure the slave through the transmitter, and connect the slave with the receiver through the ibus interface.

- ▶ **Editing :**
 - Optimized keyboard function for model naming and added special characters
 - Optimized the cross cursor display in some interfaces
 - Optimize the interface sliding effect (when sliding to the limits of the menu, it will have half the rebound effect, sliding directly to the extreme and sliding back without feedback)
 - Optimized the throttle function so that the throttle stall function can be triggered in any state



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- ▶ Editing :
- Optimized the control trigger mode under the dish flying menu, add the reverse trigger function of the knob and joystick
 - Solve the problem of data reset in subsequent versions of the upgrade model
 - Modify the manual & software version update record as a help center and optimize the background file storage method (The QR code address corresponds to all manuals, quick operation guides, and version update records)
 - Modify English font to sans-serif font
 - Increase the maximum length of the model name to 25, the home page information column displays all model names, and other sub-page information. The column displays 10 digits by default. If it exceeds 10 digits, it is not displayed at the back and three dots are displayed.
 - Remove the power indicator of the receiver in the information bar, and add a two-way protocol to the receiver without a code reminder and you can click to enter the code
 - Adjusted the interaction effect of the sliding screen trigger to solve the stuck screen caused by slow interface stop time when slow sliding illusion

Precautions

- The model data will be reset after the update is completed
- The receiver and transmitter must be bound again after the update

After the above steps are completed, the system will function as normal.



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- ▶ **新增功能：**
- 新增高频头接口支持 PPM 协议高频头
 - 新增高频头接口支持 Crossfire 协议高频头 (当前仅支持通道传输)
 - 新增模型数据传导功能 (搭配上位机使用)

- ▶ **修改功能：**
- 修复 USB 模拟器偶尔断连的 BUG
 - 修复切换摇杆模式后摇杆与微调不对应的 BUG
 - 修复模型数据低概率出现自动复位的 BUG

注意事项

- 更新完成后模型被复位 (用户配套的模型需要重新调试参数)
- 更新完成后需重新与接收机对码

以上步骤完成后, 可正常使用。

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- ▶ **New Features：**
- Added support for third party RF modules
 - Added RF UI that supports Crossfire and related protocol (currently only support channel transmission)
 - Added new model data transmission function (used with computer)

- ▶ **Editing：**
- Optimize bug that caused the USB simulator mode to disconnect occasionally
 - Optimize a bug with stick assignment not working correctly after changing stick mode
 - Optimize bug causing model data to occasionally reset

Precautions

- The model data will be reset after the update is completed (The user will have to set their models up again)
- The receiver and transmitter must be bound again after the update

After the above steps are completed, the system will function as normal.