



Version list Noble NB4 transmitter software/Noble NB4 软件版本更新记录

Software version 软件版本	2.0.83	Date 日期	3/2020
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- ▶ **新增功能 :**
 - 模型数据导入 / 导出功能
 - 主界面快捷操作功能

- ▶ **修改功能 :**
 - 优化计时器功能，将语音报时全部归入系统声音
 - 优化计时器功能，倒计时后正计时最小设置时间由 10 秒变更为 0 秒

注意事项

- 更新完成后模型被复位
- 更新完成后需重新与接收机对码

以上步骤完成后，可正常使用。

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- ▶ **New Features:**
 - Model data import / export function
 - Main interface shortcut operation function

 - ▶ **Changes:**
 - Optimized the timer function, and all the vocal feedback are classified as system sound
 - Optimized the timer function, the minimum setting time of the countdown after the countdown was changed from 10 seconds to 0 seconds

Precautions

- The model data will be reset after the update is completed
- After the update is completed, it is necessary to rebind the receiver to the transmitter

After the above steps are completed, the product can be used normally.



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Software version 软件版本	2.0.79	Date 日期	11/2019
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- ▶ **新增功能 :**
 - 增加单向模式下修改舵机响应速度退出的提示
- ▶ **修改功能 :**
 - 修复开关及按键测试菜单 BUG
 - 解决开关机时概率性模型参数丢失的问题

注意事项

- 更新完成后模型被复位（除了 2.0.77 版本）
- 更新完成后需重新与接收机对码

以上步骤完成后，可正常使用。

注：以上版本更新记录基于 2.0.75 版本。

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- ▶ **New Features:**
 - Added prompt to modify the servo response speed when exiting the one-way mode menu
 - ▶ **Changes:**
 - Fixed switch and button bugs in the test menu
 - Fixed bug that erased some model parameters when powered on and off

Precautions

- The model is reset after the update is completed (except for version 2.0.77)
 - After the update is completed, it is necessary to rebind the receiver to the transmitter
- After the above steps are completed, the product can be used normally.

Note: The changelog is based on the 2.0.75 version.



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Software version 软件版本	2.0.78	Date 日期	11/2019
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- ▶ 新增功能 :
 - 无
- ▶ 修改功能 :
 - 解决开关机时概率性模型参数丢失的问题

注意事项

- 更新完成后模型被复位（除了 2.0.75 版本）
- 更新完成后需重新与接收机对码

以上步骤完成后，可正常使用。

注：以上版本更新记录基于 2.0.75 版本。

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- ▶ New Features:
 - None
 - ▶ Changes:
 - Fixed bug that erased some model parameters when powered on and off

Precautions

- The model is reset after the update is completed (except for version 2.0.75)
- After the update is completed, it is necessary to rebind the receiver to the transmitter

After the above steps are completed, the product can be used normally.

Note: The changelog is based on the 2.0.75 version.



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Software version 软件版本	2.0.75	Date 日期	08/2019
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- **新增功能 :**
- 新增日语菜单界面
 - 新增主菜单排序及隐藏功能
 - 新增初学者模式（默认为隐藏且未开启）
 - 新增说明书菜单
 - 新增氛围灯可以用来做电量指示功能
 - 新增旋钮及 TR 可以分配做 2、3 档开关使用功能
 - 新增关于菜单下显示 MCU UID 信息
- **修改功能 :**
- 修复 USB 模拟器可能断连的 bug
 - 修复按键分配旋钮反向无效的 bug
 - 修复主界面通道显示抖动的 bug
 - 优化接收机输出模式相关功能
- 注意事项**
- 更新完成后模型被复位
 - 更新完成后需重新与接收机对码
- 以上步骤完成后，可正常使用。
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- **New Features:**
- Add a Japanese
 - Add the main menu sorting and hiding function
 - Add a beginner mode (the default is hidden and not open)
 - Add a manual menu
 - Add the function that the new ambient light can be used to do the power indicator
 - Add the function that the new knob and TR can be assigned to do the 2, 3 gear switch
 - Added information about the MCU UID displayed under the menu
- **Changes:**
- Optimize the bug that the USB emulator may be disconnected
 - Optimize the bug that the button assignment knob is invalid in the reverse direction
 - Optimize the bug that the main interface channel displays jitter
 - Optimize the receiver output mode related functions

Precautions

- The model data will be reset after the update is completed
- After the update is completed, it is necessary to rebind the receiver to the transmitter

After the above steps are completed, the product can be used normally.



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Software version 软件版本	2.0.67	Date 日期	07/2019
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- **新增功能 :**
- 通道个数可用户自定义 4、6、8 个
 - Break D/R 可单独调节
 - TR 功能外设操作生效时弹窗提示
 - 所有操作都可带震动提示
 - 新增 Mini-Z EVO 模式
 - 最小背光亮度可调节（可关闭背光）
 - LED 灯亮度可调节
- **修改功能 :**
- 优化系统结构
 - 优化操控触摸响应速度
 - 优化英文界面字体
 - 优化主界面 CH1、CH2 通道显示逻辑
 - 优化部分功能的语音提示
 - 优化系统开机启动速度
 - 优化系统设置菜单下的功能排序
 - 优化按键设定菜单功能

注意事项

- 更新完成后模型被复位
- 更新完成后用户需自行校准手轮和扳机
- 更新完成后需重新与接收机对码

以上步骤完成后，可正常使用。

- **New Features :**
- The user can now choose between 4, 6 and 8 channels
 - The breaks D/R can now be adjusted by itself
 - Pop up added when using the TR function
 - All operations can now have a vibration effect
 - Added Mini-D EVO mode
 - Minimum brightness can now be set to 0 (Turning off backlight)
 - LED brightness can now be adjusted
- **Editing :**
- Optimized the system architecture
 - Optimized touch to increase speed
 - Optimized English fonts
 - Optimized the display logic for channels one and 2 at the main menu
 - Optimizations of voice prompts
 - Optimizations to increase boot speed



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Editing :

- Optimized function sorting in the function menu
- Optimized the key select function

Precautions

- The model is reset after the update is completed
- After the update is completed, the user needs to calibrate the steering wheel and the trigger
- The receiver and transmitter must be bound again after the update

After the above steps are completed, the system will function as normal.



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Software version 软件版本	1.0.41	Date 日期	06/2019
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- ▶ 新增功能 :
 - 增加了 EVO 模式

- ▶ 修改功能 :
 - 修改优化方向和油门死区
 - 修改优化资源头文件和校验改为 STM32 硬件 CRC 校验以加快开机速度
 - 修改优化 ADC 通道相互干扰的 BUG
 - 菜单界面下左右滑屏菜单图标会错位

注意事项

- 更新完成后模型被复位

以上步骤完成后，可正常使用。

- ▶ New Features :
 - Added EVO mode

- ▶ Editing :
 - Optimize the steering and throttle dead zones
 - Optimize the resource header file and verified that the STM32 hardware CRC is changed to speed up the boot
 - Optimize bug causing interference on ADC channels
 - Optimize the issue that when swiping left and right on the screen causing menu icons will be placed under the menu UI

Precautions

- The model is reset after the update is completed

After the above steps are completed, the system will function as normal.



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Software version 软件版本	1.0.37	Date 日期	03/2019
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- 新增功能 : • 增加中文显示能

注意事项

- 更新完成后模型被复位

以上步骤完成后，可正常使用。

- New Features : • Added the size of Chinese text

Precautions

- The model is reset after the update is completed

After the above steps are completed, the system will function as normal.



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Software version 软件版本	1.0.36	Date 日期	01/2019
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- **修改功能 :**
- 更新了高频资源
 - 资源模块中增加了版本判断
 - 修改了默认温度和长度默认单位

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- **Editing :**
- Updated RF resources
 - Version info has been added to the resource module data
 - The default temperature and length units have been modified



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Software version 软件版本	1.0.32-Beta	Date 日期	12/2018
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- **修改功能 :**
- 优化系统延时性能
 - 优化通道值计算算法
 - 优化更新高频库程序

注意事项

- 更新完成后模型被复位
- 更新完成后用户需自行校准手轮和扳机
- 更新完成后需进行高频 RF 更新，接收机更新

以上步骤完成后，可正常使用。

- **Editing :**
- Optimize system latency performance
 - Optimize the channel value calculation algorithm
 - Optimize and update the high frequency library

Precautions

- The model is reset after the update is completed
- After the update is completed, the user needs to calibrate the steering wheel and the trigger
- RF update, receiver update needed after update is completed

After the above steps are completed, the system will function as normal.



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Software version 软件版本	1.0.30	Date 日期	10/2018
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► 新增功能 :

- 新增双向回传功能
- 新增传感器功能
- 新增 Range TEST 功能
- 新增舵机频率设置功能
- 新增接收机输出模式设置功能
- 新增 I.BUS 通道扩展功能
- 新增接收机更新功能
- 新增 USB 模拟器功能

► New Features :

- Added two-way return function
- Added sensor function
- Added Range TEST function
- Added servo frequency setting function
- Added receiver output system setting function
- Added I.BUS channel extension function
- Added receiver update function
- Added USB emulator function